LMX2430,LMX2433,LMX2434

LMX2430/LMX2433/LMX2434 PLLatinum Dual High Frequency Synthesizer for RF Personal CommunicationsLMX24303.0 GHz/0.8 GHzLMX24333.6 GHz/1.7 **GHzLMX24345.0 GHz/2.5 GHz**

Literature Number: SNAS187B

LMX2430/LMX2433/LMX2434 PLLatinum™ Dual High Frequency Synthesizer for RF Personal Communications LMX2430 3.0 GHz/0.8 GHz

LMX2433 3.6 GHz/1.7 GHz

LMX2434 5.0 GHz/2.5 GHz

General Description

The LMX243x devices are high performance frequency synthesizers with integrated dual modulus prescalers. The LMX243x devices are designed for use as RF and IF local oscillators for dual conversion radio transceivers.

A 32/33 or a 16/17 prescale ratio can be selected for the 5.0 GHz LMX2434 RF synthesizer. An 8/9 or a 16/17 prescale ratio can be selected for both the LMX2430 and LMX2433 RF synthesizers. The IF circuitry contains an 8/9 or a 16/17 prescaler. Using a proprietary digital phase locked loop technique, the LMX243x devices generate very stable, low noise control signals for RF and IF voltage controlled oscillators. Both the RF and IF synthesizers include a two-level programmable charge pump. Both the RF and IF synthesizers have dedicated Fastlock circuitry with integrated timeout counters. Furthermore, only a single word write is required to power up and tune the synthesizers to a new frequency.

Serial data is transferred to the devices via a three-wire interface (DATA, LE, CLK). A low voltage logic interface allows direct connection to 1.8V devices. Supply voltages from 2.25V to 2.75V are supported . The LMX243x family features low current consumption:

LMX2430 (3.0 GHz/ 0.8 GHz) — 2.8 mA/ 1.4 mA, LMX2433 (3.6 GHz/ 1.7 GHz) — 3.2 mA/ 2.0 mA, LMX2434 (5.0 GHz/ 2.5 GHz) — 4.6 mA/ 2.4 mA at 2.50V.

The LMX243x devices are available in 20-Pin TSSOP and 20-Pin UTCSP surface mount plastic packages.

Features

- **n** Low Current Consumption
- 2.25V to 2.75V Operation
- Selectable Synchronous or Asynchronous Powerdown Mode
- Selectable Dual Modulus Prescaler:

- Programmable Charge Pump Current Levels RF and IF: 1 or 4 mA
- Fastlock™ Technology with Integrated Timeout Counters
- Digital Filtered Lock Detect Output
- n Analog Lock Detect Output (supports both Push-Pull and Open Drain configurations)
- 1.8V MICROWIRE Logic Interface
- Available in 20-Pin TSSOP and 20-Pin UTCSP

Applications

- Mobile Handsets (GSM, GPRS, W-CDMA, CDMA, PCS, AMPS, PDC, DCS)
- Cordless Handsets (DECT, DCT)
- **Wireless Data**
- Cable TV Tuners

Note:

1 (2) refers to Pin #1 of the 20-Pin UTCSP and Pin #2 of the 20-Pin TSSOP

Connection Diagrams Ultra Thin Chip Scale Package (SLE) (Top View) DATA CLK Vcc GND 17° $\mathbf 1$ 18 $\overline{\mathsf{LE}}$ 20 $1\,9$ \circ $\overline{2}$ 16 FinlF $_{\rm Vec}$ $\frac{1}{15}$ ${\sf EN}$ $\mathbf 3$ $FinRF^*$ $\overline{14}$ FinRF CPoutlF $\boldsymbol{\Lambda}$ $\begin{array}{c} \hline 13 \end{array}$ GND ENosc $\overline{5}$ OSCout/FLoutIF $1\,2$ 6 CPoutRF $\overline{10}$ $\bf{8}$ 9 OSCin $\bar{\tau}$ 11 GND $Ftest/LD$ Vcc FLoutRF 20053539

Pin Descriptions

Pin Descriptions (Continued)

Ordering Information

Absolute Maximum Ratings (Notes 1,

2, 3)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Recommended Operating Conditions (Note 1)

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Recommended Operating Conditions indicate conditions for which the device is intended to be functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, refer to the Electrical Characteristics section. The guaranteed specifications apply only for the conditions listed.

Note 2: This device is a high performance RF integrated circuit with an ESD rating <2 kV and is ESD sensitive. Handling and assembly of this device should only be done at ESD protected work stations. **Note 3:** GND = 0V

Electrical Characteristics

Vcc = EN = $2.5V$, $-40^{\circ}C \le T_A \le +85^{\circ}C$, unless otherwise specified

Note 4: Some of the values in this range are illegal divide ratios (B < A). To obtain continuous legal division, the Minimum Divide Ratio must be calculated. Use N ≥ P * (P-1), where P is the value of the prescaler selected.

Note 5: Refer to the LMX243x FinRF Sensitivity Test Setup section

Note 6: Refer to the LMX243x Charge Pump Test Setup section

Note 7: Refer to the Charge Pump Current Specification Definitions for details on how these measurements are made.

Note 8: Refer to the LMX243x OSCin Sensitivity Test Setup section

Note 9: Refer to the LMX243x Serial Data Input Timing section

Note 10: Normalized Phase Noise Contribution is defined as : L_N(f) = L(f) − 20 log (N) − 10 log (f_{COMP}), where L(f) is defined as the single side band phase noise measured at an offset frequency, f, in a 1 Hz bandwidth. The offset frequency, f, must be chosen sufficiently smaller than the PLL's loop bandwidth, yet large enough to avoid substantial phase noise contribution from the reference source. N is the value selected for the feedback divider and f_{COMP} is the RF/IF phase/ frequency detector comparison frequency.

Note 11: The synthesizer phase noise is measured with the LMX2430TM/LMX2430SLE Evaluation boards and the HP8566B Spectrum Analyzer.

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∆V = Voltage offset from the positive and negative rails. Dependent on the VCO tuning range relative to Vcc and GND. Typical values are between 0.5V and 1.0V.

V_{CPout} refers to either V_{CPoutRF} or V_{CPoutIF} I_{CPout} refers to either I_{CPoutRF} or I_{CPoutIF}

Charge Pump Output Current Magnitude Variation Vs Charge Pump Output Voltage

$$
I_{CPout} \text{Vs } V_{CPout} = \frac{(|11| - |13|)}{(|11| + |13|)} \times 100\%
$$

$$
= \frac{(|14| - |16|)}{(|14| + |16|)} \times 100\%
$$

Charge Pump Output Sink Current Vs Charge Pump Output Source Current Mismatch

$$
I_{\text{CPout}} \text{Sink Vs } I_{\text{CPout}} \text{ Source} = \frac{|12| - |15|}{\frac{1}{2} (|12| + |15|)} \times 100\%
$$

Charge Pump Output Current Magnitude Variation Vs Temperature

$$
I_{CPout} \text{ Vs } T_A = \frac{|I_2| \left| \frac{1}{T_A} - |I_2| \right|_{T_A = 25^\circ \text{C}}}{|I_2| \left| \frac{1}{T_A = 25^\circ \text{C}}} \times 100\%
$$

$$
= \frac{|I_5| \left| \frac{1}{T_A} - |I_5| \right|_{T_A = 25^\circ \text{C}}}{|I_5| \left| \frac{1}{T_A = 25^\circ \text{C}}} \times 100\%
$$

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LMX243x UTCSP FinRF Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25°C$

LMX243x UTCSP FinRF Input Impedance Table (Continued)

 $Vcc = EN = 2.50V, T_A = +25[°]C$

LMX243x TSSOP FinRF Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25°C$

LMX243x TSSOP FinRF Input Impedance Table (Continued)

 $Vcc = EN = 2.50V, T_A = +25[°]C$

LMX243x UTCSP FinIF Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25°C$

LMX243x TSSOP FinIF Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25[°]C$

LMX243x UTCSP OSCin Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25°C$

LMX243x TSSOP OSCin Input Impedance Table

 $Vcc = EN = 2.50V, T_A = +25[°]C$

The block diagram above illustrates the setup required to measure the LMX243x device's RF charge pump sink current. The same setup is used for the LMX2430TM Evaluation Board. The purpose of this test is to assess the functionality of the RF charge pump. The IF charge pump is evaluated in the same way.

This setup uses an open loop configuration. A power supply is connected to Vcc. By means of a signal generator, a 10 MHz signal is typically applied to the FinRF pin. The signal is one of two inputs to the phase/ frequency detector (PFD). The 3 dB pad provides a 50 Ω match between the PLL and the signal generator. The OSCin pin is tied to Vcc. This establishes the other input to the PFD. Alternatively, this input can be tied directly to the ground plane. The EN and ENosc pins are also both tied to Vcc. A Semiconductor Parameter Analyzer is connected to the CPoutRF pin and used to measure the sink, source, and TRI-STATE leakage currents.

Let F_r represent the frequency of the signal applied to the OSCin pin, which is simply zero in this case (DC), and let F_p represent the frequency of the signal applied to the FinRF

pin. The PFD is sensitive to the rising edges of F_r and F_p . Assuming positive VCO characteristics (RF_CPP bit = 1); the charge pump turns ON, and sinks current when the first rising edge of F_p is detected. Since F_r has no rising edge, the charge pump continues to sink current indefinitely. In order to measure the RF charge pump source current, the RF_CPP bit is simply set to 0 (negative VCO characteristics) in CodeLoader. Similarly, in order to measure the TRI-STATE leakage current, the RF_CPT bit is set to 1.

The measurements are typically taken over supply voltage and temperature. The measurements are also typically taken at the HIGH and LOW charge pump current gains. The charge pump current gain can be controlled by the RF_CPG bit in CodeLoader. Once the charge pump currents are determined, the (i) charge pump output current magnitude variation versus charge pump output voltage, (ii) charge pump output sink current versus charge pump output source current mismatch, and (iii) charge pump output current magnitude versus tempeature, can be calculated. Refer to the **Charge Pump Current Specifications Definition** for more details.

The block diagram above illustrates the setup required to measure the LMX243x device's RF input sensitivity level. The same setup is used for the LMX2430TM Evaluation Board. The purpose of this test is to measure the acceptable signal level to the FinRF input of the PLL chip. Outside the acceptable signal range, the feedback divider begins to divide incorrectly and miscount the frequency. The FinIF sensitivity is evaluated in the same way.

The setup uses an open loop configuration. A power supply is connected to Vcc. The IF PLL is powered down (IF_PD bit = 1). By means of a signal generator, an RF signal is applied to the FinRF pin. The 3 dB pad provides a 50Ω match between the PLL and the signal generator. The EN, ENosc, and OSCin pins are all tied to Vcc. The N value is typically set to 10000 in CodeLoader, i.e. RF_B word = 156 and RF_A word = 16 for RF_P bit = 0 (LMX2434) or RF_P bit = 1 (LMX2430 and LMX2433). The feedback divider output is routed to the Ftest/LD pin by selecting the RF_N/2 Frequency word (MUX[3:0] word = 15) in CodeLoader. A Universal Counter is connected to the Ftest/LD pin and used to monitor the output frequency of the feedback divider. The

expected frequency should be the signal generator frequency divided by twice the corresponding counter value, i.e. 20000. The factor of two comes in because the LMX43x device has an internal /2 circuit which is used to provide a 50% duty cycle.

Sensitivity is typically measured over frequency, supply voltage and temperature. In order to perform the measurement, the temperature, frequency, and supply voltage is set to a fixed value and the power level of the signal at FinRF is varied. Sensitivity is reached when the frequency error of the divided RF input is greater than or equal to 1 Hz. The power attenuation from the cable and the 3 dB pad must be accounted for. The feedback divider will actually miscount if too much or too little power is applied to the FinRF input. Therefore, the allowed input power level will be bounded by the upper and lower sensitivity limits. In a typical application, if the power level to the FinRF input approaches the sensitivity limits, this can introduce spurs or cause degradation to the phase noise. When the power level gets even closer to these limits, or exceeds it, then the RF PLL loses lock.

The block diagram above illustrates the setup required to measure the LMX243x device's OSCin buffer sensitivity level. The same setup is used for the LMX2430TM Evaluation Board. This setup is similar to the FinRF sensitivity setup except that the signal generator is now connected to the OSCin pin and both Fin pins are tied to Vcc. The 51Ω shunt resistor matches the OSCin input to the signal generator. The R counter is typically set to 1000, i.e. RF_R word = 1000 or IF_R word = 1000. The reference divider output is routed to the Ftest/LD pin by selecting the RF_R/ 2 Frequency word $(MUX[3:0]$ word = 14) or the IF_R/ 2 Frequency word (MUX[3:0] word = 12) in CodeLoader. A Universal Counter is connected to the Ftest/LD pin and is used to monitor the output frequency of the reference divider. The expected frequency should be the signal generator frequency divided by twice the corresponding counter value, i.e. 2000. The factor of two comes in because the LMX243x device has an internal /2 circuit which is used to provide a 50% duty cycle.

In a similar way, sensitivity is typically measured over frequency, supply voltage and temperature. In order to perform the measurement, the temperature, frequency, and supply voltage is set to a fixed value and the power level (voltage level) of the signal at OSCin is varied. Sensitivity is reached when the frequency error of the divided input signal is greater than or equal to 1 Hz.

The block diagram above illustrates the setup required to measure the LMX243x device's RF input impedance. The same setup is used for the LMX2430TM Evaluation Board. Measuring the device's input impedance facilitates the design of appropriate matching networks to match the PLL to the VCO, or in more critical situations, to the characteristic impedance of the printed circuit board (PCB) trace, to prevent undesired transmission line effects. The FinIF input impedance is evaluated in the same way.

Before the actual measurements are taken, the Network Analyzer needs to be calibrated, i.e. the error coefficients need to be calculated. The Network Analyzer's calibration standard is used to calculate these coefficients. The calibration standard includes an open, short and a matched load. A 1-port calibration is implemented here.

To calculate the coefficients, the PLL chip is first removed from the PCB. A piece of semi-rigid coaxial cable is then soldered to the pad on the PCB which is equivalent to the FinRF pin on the PLL chip. Proper grounding near the exposed tip of the semi-rigid coaxial cable is required for accurate results. Note that the DC blocking capacitor is removed for this test. The Network Analyzer port is then connected to the other end of the semi-rigid coaxial cable. In this way, the semi-rigid coaxial cable acts as a transmission line. This transmission line adds electrical length and produces an offset from the reference plane of the Network Analyzer; therefore, it must be included in the calibration. The desired operating frequency is then set. The typical frequency range selected for the LMX243x device's RF synthesizer is from 100 MHz to 6000 MHz.

The Network Analyzer calculates the calibration coefficients based on the measured S_{11} parameters. With this all done, calibration is now complete.

The PLL chip is then placed on the PCB. A power supply is then connected to Vcc. The EN, ENosc, and OSCin pins are all tied to Vcc. Alternatively, the OSCin pin can be tied to ground. In this setup, the complementary input (FinRF*) is AC coupled to ground. With the Network Analyzer still connected to the semi-rigid coaxial cable, the measured FinRF impedance is displayed.

The OSCin input impedance is measured in the same way. The impedance is measured when the oscillator buffer is powered up (ENosc is set HIGH) and when the oscillator buffer is powered down (ENosc pin is set LOW).

LMX243x Serial Data Input Timing

Notes:

- 1. DATA is clocked into the 24-bit shift register on the rising edge of CLK
- 2. The MSB of DATA is shifted in first.

1.0 Functional Description

The basic phase-lock-loop (PLL) configuration consists of a high-stability crystal reference oscillator, a frequency synthesizer such as the National Semiconductor LMX243x, a voltage controlled oscillator (VCO), and a passive loop filter. The frequency synthesizer includes a phase detector, current mode charge pump, programmable reference R and feedback N frequency dividers. The VCO frequency is established by dividing the crystal reference signal down via the reference divider to obtain a comparison reference frequency. This reference signal, f_r, is then presented to the input of a phase/ frequency detector and compared with the feedback signal, f_p , which was obtained by dividing the VCO frequency down by way of the feedback divider. The phase/ frequency detector measures the phase error between the f_r and f_p signals and outputs control signals that are directly proportional to the phase error. The charge pump then pumps charge into or out of the loop filter based on the magnitude and direction of the phase error. The loop filter converts the charge into a stable control voltage for the VCO. The phase/frequency detector's function is to adjust the voltage presented to the VCO until the feedback signal's frequency and phase match that of the reference signal. When this "Phase-Locked" condition exists, the VCO frequency will be N times that of the comparison frequency, where N is the feedback divider ratio.

1.1 REFERENCE OSCILLATOR INPUT

The reference oscillator frequency for both the RF and IF PLLs is provided from an external reference via the OSCin pin. The reference buffer circuit supports input frequencies from 5 to 40 MHz with a minimum input sensitivity of 0.5 V_{pp} . The reference buffer circuit has an approximate Vcc/2 input threshold and can be driven from an external AC coupled source. Typically, the OSCin pin is connected to the output of a crystal oscillator.

1.2 REFERENCE DIVIDERS (R COUNTERS)

The reference dividers divide the reference input signal, OSCin, by a factor of R. The output of the reference divider circuits feeds the reference input of the phase detector. This reference input to the phase detector is often referred to as the comparison frequency. The divide ratio should be chosen such that the maximum phase comparison frequency $(f_{\rm COM^{-}})$ PRF or f_{COMPIF}) of 10 MHz is not exceeded.

The RF and IF reference dividers are each comprised of 15-bit CMOS binary counters that support a continuous integer divide ratio from 3 to 32767. The RF and IF reference divider circuits are clocked by the output of the reference buffer circuit which is common to both. Refer to **Sections 2.4.1** and **2.7.1** for details on how to program the RF_R and IF_R counters.

1.3 PRESCALERS

The FinRF and FinIF input pins drive the input of a differential-pair amplifier. The output of the differential-pair amplifier drives a chain of D-type flip-flops in a dual modulus configuration. The output of the prescaler is used to clock the subsequent feedback dividers. The RF PLL complementary inputs can be driven differentially, or the negative input can be AC coupled to ground through an external capacitor for single ended configuration. A 16/17 or a 32/33 prescale ratio can be selected for the 5.0 GHz LMX2434 RF synthesizer. An 8/9 or a 16/17 prescale ratio can be selected for both the LMX2430 and LMX2433 RF synthesizers. The IF PLL is single ended. An 8/9 or a 16/17 prescale ratio can be selected for the IF synthesizer.

1.4 PROGRAMMABLE FEEDBACK DIVIDERS (N COUNTERS)

The programmable feedback dividers operate in concert with the prescalers to divide the input signal, Fin, by a factor of N. The output of the programmable reference divider is provided to the feedback input of the phase detector circuit. The divide ratio should be chosen such that the maximum phase comparison frequency (f_{COMPRF} or f_{COMPIF}) of 10 MHz is not exceeded.

The programmable feedback divider circuit is comprised of an A counter (swallow counter) and a B counter (programmble binary counter). For both the LMX2430 and LMX2433, the RF_A counter is a 4-bit swallow counter, programmable from 0 to 15. The LMX2434 RF_A counter is a 5-bit swallow counter, programmable from 0 to 31. The LMX243x IF_A counter is a 4-bit swallow counter, programmable from 0 to 15. For both the LMX2430 and LMX2433, the RF_B counter is a 15-bit binary counter, programmable from 3 to 32767. The LMX2434 RF_B counter is a 14-bit binary counter, programmable from 3 to 16383. The LMX243x IF_B is a 14-bit binary counter programmable from 3 to 16383. A continuous integer divide ratio is achieved if $N \ge P^*$ (P-1), where P is the value of the prescaler selected. Divide ratios less than the minimum continuous divide ratio are achievable as long as the binary programmable counter value is greater than the swallow counter value ($B \geq A$). Refer to **Sections 2.5.1.1, 2.5.1.2, 2.5.2.1, 2.5.2.2, 2.8.1,** and **2.8.2** for details on how to program the A and B counters. The following equations are useful in determining and programming a particular value of N:

 $N = (P \times B) + A$

 $Fin = N \times f_{COMP}$

Definitions:

f_{COMP}: RF or IF phase detector comparison frequency

- Fin: RF or IF input frequency
- A: RF_A or IF_A counter value
- B: RF_B or IF_B counter value
- P: Preset modulus of the dual modulus prescaler LMX2430 RF synthesizer: $P = 8$ or 16 LMX2433 RF synthesizer: $P = 8$ or 16 LMX2434 RF synthesizer: $P = 16$ or 32 LMX243x IF synthesizer: $P = 8$ or 16

1.5 PHASE/ FREQUENCY DETECTORS

The RF and IF phase/ frequency detectors (PFD) are driven from their respective N and R counter outputs. The maximum frequency for both the RF and IF phase detector inputs is 10 MHz. The PFD outputs control the respective charge pumps. The polarity of the pump-up or pump-down control signals are programmed using the **RF_CPP** or **IF_CPP** control bits, depending on whether the RF or IF VCO characteristics are positive or negative. Refer to **Sections 2.4.2** and **2.7.2** for more details. The PFDs have a detection range of −2π to +2π. The PFDs also receive a feedback signal from the charge pump in order to eliminate dead zone.

1.0 Functional Description (Continued)

1.5.1 Phase Comparator and Internal Charge Pump Characteristics

Notes:

- 1. The minimum width of the pump-up and pump-down current pulses occur at the CPoutRF or CPoutIF pins when the loop is phase locked.
- 2. The diagram assumes positive VCO characteristics, i.e. RF_CPP or IF_CPP = 1.
- 3. f_r is the PFD input from the reference divider (R counter).
- 4. f_p is the PFD input from the programmable feedback divder (N counter).
- 5. CPout refers to either the RF or IF charge pump output.

1.6 CHARGE PUMPS

The charge pump directs charge into or out of an external loop filter. The loop filter converts the charge into a stable control voltage which is applied to the tuning input of the VCO. The charge pump steers the VCO control voltage towards Vcc during pump-up events and towards GND during pump-down events. When locked, CPoutRF or CPoutIF are primarily in a TRI-STATE mode with small corrections occuring at the phase comparator rate. The charge pump output current magnitude can be selected by toggling the **RF_CPG** or **IF_CPG** control bits.

1.7 MICROWIRE SERIAL INTERFACE

The programmable register set is accessed via the MI-CROWIRE serial interface. A low voltage logic interface allows direct connection to 1.8V devices. The interface is comprised of three signal pins: CLK, DATA and LE. Serial data is clocked into the 24-bit shift register on the rising edge of CLK. The last two bits decode the internal control register address. When LE transitions HIGH, DATA stored in the shift register is loaded into one of four control registers depending on the state of the address bits. The MSB of DATA is loaded in first. The synthesizers can be programmed even in power down mode. A complete programming description is provided in **Section 2.0 Programming Description**.

1.8 MULTI-FUNCTION OUTPUTS

The LMX243x device's Ftest/LD output pin is a multi-function output that can be configured as a general purpose CMOS TRI-STATE output, push-pull analog lock detect output, open-drain analog lock detect output, digital filtered lock detect output, or used to monitor the output of the various reference divider (R counter) or feedback divider (N counter) circuits. The Ftest/LD control word is used to select the desired output function. When the PLL is in powerdown mode, the Ftest/LD output is disabled and is in a high impedance state. A complete programming description of the multi-function output is provided in **Section 2.10**.

1.8.1 Push-Pull Analog Lock Detect Output

An analog lock detect status generated from the phase detector is available on the Ftest/LD output pin if selected. A push-pull configuration can be selected for the lock detect output signal. With this configuration, the lock detect output goes HIGH when the charge pump is inactive. It goes LOW when the charge pump is active during a comparison cycle. Narrow low going pulses are observed when the charge pump turns on.

There are three separate push-pull analog lock detect signals that are routed to the multiplexer. Two of these monitor the lock status of the individual synthesizers. The third detects the condition when both the RF and IF synthesizers are in a locked state. External circuitry is required to provide a steady DC signal to indicate when the PLL is in a locked state. Refer to **Section 2.10** for details on how to program the different push-pull analog lock detect options.

1.8.2 Open-Drain Analog Lock Detect Output

The lock detect output can be an open-drain configuration. In this configuration, the lock detect output goes to a high impedance state when the charge pump is inactive. It goes LOW when the charge pump is active during a comparison cycle. When a pull-up resistor is used, narrow low going pulses are observed when the charge pump turns on.

Similarly, three separate open-drain analog lock detect signals are routed to the multiplexer. Two of these monitor the lock status of the individual synthesizers. The third detects the condition when both the RF and IF synthesizers are in a locked state. External circuitry is required to provide a steady DC signal to indicate when the PLL is in a locked state. Refer to **Section 2.10** for details on how to program the different open-drain analog lock detect options.

1.0 Functional Description (Continued)

1.8.3 Digital Filtered Lock Detect Output

A digital filtered lock detect status generated from the phase detector is also available on the Ftest/LD output pin if selected. The lock detect digital filter compares the difference bewteen the phases of the inputs to the PFD to an RC generated delay of approximately 15 ns. If the phase error is less than the 15 ns RC delay for 5 consecutive reference

cycles, the PLL enters a locked state (HIGH). Once in lock, the RC delay is changed to approximately 30 ns. Once the phase error becomes greater than the 30 ns RC delay, the PLL falls out of lock (LOW). When the PLL is in powerdown mode, the Ftest/LD output is forced LOW. A flow chart of the digital filtered lock detect output is shown below.

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Similarly, three separate digital filtered lock detect signals are routed to the multiplexer. Two of these monitor the lock status of the individual synthesizers. The third detects the condition when both the RF and IF synthesizers are in a locked state. External circuitry is not required when the digital filtered lock detect option is selected. Refer to **Section 2.10** for details on how to program the different digital filtered lock detect options.

1.0 Functional Description (Continued)

1.8.4 Reference Divider and Feedback Divider Output

The outputs of the various N and R dividers can be monitored by selecting the appropriate Ftest/LD word. This is essential when performing OSCin or Fin sensitivity measurements. Refer to the **LMX243x FinRF Sensitivity Test Setup** or **LMX243x OSCin Sensitivity Test Setup** sections for more details. Note, the R and N outputs that are routed to the Ftest/LD are R/2 and N/2 respectively. The internal /2 circuit is used to provide a 50% duty cycle. Refer to **Section 2.10** for more details on how to route the appropriate divider output to the Ftest/LD pin.

1.9 FASTLOCK OUTPUT

The LMX243x Fastlock feature allows a faster loop response time during lock aquisition. The loop response time (lock time) can be approximately halved if the loop bandwidth is doubled. In order to achieve this, the same gain/ phase relationship should be maintained when the loop bandwidth is doubled. When the FLoutRF or OSCout/ FLoutIF pins are configured as FastLock outputs, an open drain device is enabled. The open drain device switches in a resistor parallel, and of equal value, to R2 of the external loop filter. The loop bandwidth is effectively doubled and stability is maintained. Once locked to the correct frequency, the PLL will return to a steady state condition.The LMX243x offers two methods to achieve Fastlock: manual and automatic. Manual Fastlock is achieved by increasing the charge pump current from 1 mA (RF_CPG/ IF_CPG Bit = 0) in the steady state mode, to 4 mA (RF_CPG/ IF_CPG Bit = 1) in Fastlock mode. Automatic Fastlock is achieved by programming the timeout counter register (RF_TOC/ IF_TOC) with the appropriate number of phase comparison cycles that the RF/ IF synthesizer will spend in the Fastlock state. Refer to **Sections 2.6 and 2.9** for details on how to configure the FLoutRF or OSCout/ FLoutIF output to an open drain Fastlock output.

1.10 COUNTER RESET

When the RF_RST/ IF_RST bit is enabled, both the feedback divider (RF_N/ IF_N) and reference divider (RF_R/ IF_R) are held at their load point. When the device is programmed to normal operation, both the feedback divider and reference divder are enabled and resume counting in close alignment to each other. Refer to **Sections 2.4.5 and 2.7.5** for more details.

1.11 POWER CONTROL

The LMX243x device can be asynchronously powered down when the EN pin is set LOW, independent of the state of the powerdown bits. Note that the OSCout/ FLoutIF pin can still

be enabled if the ENosc pin is set HIGH, independent of the state of the EN pin. This capability allows the oscillator buffer to be used as a crystal oscillator. When EN is set HIGH, powerdown is controlled through the MICROWIRE. The powerdown word is comprised of the **RF_PD**/ **IF_PD** bit, in conjuction with the **RF_CPT**/ **IF_CPT** bit. The powerdown control word is used to set the operating mode of the device. Refer to **Sections 2.4.4, 2.5.4, 2.7.4**, and **2.8.4** for details on how to program the RF or IF powerdown bits.

When either synthesizer is powered down, the respective prescaler, phase detector, and charge pump circuit is disabled. The CPoutRF/ CPoutIF, FinRF/ FinIF, and FinRF* pins are all forced to a high impedance state. The reference divider and feedback divider circuits are held at the load point during powerdown. The oscillator buffer is disabled when the ENosc pin is set LOW. The OSCin pin is forced to a HIGH state through an approximate 100 kΩ resistance when this condition exists. When either synthesizer is activated, the respective prescaler, phase detector, charge pump circuit, and the oscillator buffer are all powered up. The feedback divider and reference divider are held at their load point. This allows the reference oscillator, feedback divider, reference divider and prescaler circuitry to reach proper bias levels. After a finite delay, the feedback and reference dividers are enabled and they resume counting in close alignment (the maximum error is one prescaler cycle). The MICROWIRE control register remains active and capable of loading and latching data while in powerdown mode.

1.11.1 Synchronous Powerdown Mode

In this mode, the powerdown function is gated by the charge pump. When the device is configured for synchronous powerdown, the device will enter the powerdown mode upon completion of the next charge pump pulse event.

1.11.2 Asynchronous Powerdown Mode

In this mode, the powerdown function is NOT gated by the completion of a charge pump pulse event. When the device is configured for asynchronous powerdown, the part will go into powerdown mode immediately.

Note: X refers to a don't care condition.

2.0 Programming Description

2.1 MICROWIRE INTERFACE

The 24-bit shift register is loaded via the MICROWIRE interface. The shift register consists of a 21-bit *DATA[20:0] FIELD* and a 3-bit *ADDRESS[2:0] FIELD* as shown below. The ADDRESS FIELD is used to decode the internal control register address. When LE transitions HIGH, DATA stored in the shift register is loaded into one of 6 control registers depending on the state of the ADDRESS bits. The MSB of DATA is loaded into the shift register first. The DATA FIELD assignments are shown in **Section 2.3 CONTROL REGISTER CONTENT MAP**.

2.2 CONTROL REGISTER LOCATION

The ADDRESS[2:0] bits decode the internal register address. The table below shows how the ADDRESS bits are mapped into the target control register.

2.3 CONTROL REGISTER CONTENT MAP

The control register content map describes how the bits within each control register are allocated to specific control functions. The bits that are marked 0 should be programmed as such to ensure proper device operation.

2.4 R0 REGISTER

The R0 register contains the RF_R, RF_CPP, RF_CPG, RF_CPT, and RF_RST control words, in addition to two of the four bits that compose the MUX control word. The detailed descriptions and programming information for each control word is discussed in the following sections.

2.4.1 RF_R[14:0] - RF Synthesizer Programmable Reference Divider (R Counter) (R0[17:3])

The RF reference divider (RF_R) can be programmed to support divide ratios from 3 to 32767. Divide ratios less than 3 are prohibited.

2.4.2 RF_CPP - RF Synthesizer Phase Detector Polarity (R0[18])

The RF_CPP bit is used to control the RF synthesizer's phase/ frequency detector polarity based on the VCO tuning characteristics.

RF VCO Characteristics

2.4.3 RF_CPG - RF Synthesizer Charge Pump Current Gain (R0[19])

The RF_CPG bit controls the RF synthesizer's charge pump gain. Two gain levels are available.

2.4.4 RF_CPT - RF Synthesizer Charge Pump TRI-STATE (R0[20])

The RF_CPT bit allows the charge pump to be switched between a normal operating mode and a high impedance output state. This happens asynchronously with the change in the RF_CPT bit.

Furthermore, the RF_CPT bit operates in conjuction with the RF_PD bit to set a synchronous or an asynchronous powerdown mode. Refer to **Section 2.5.4** for more details on how to program the RF_PD bit.

2.4.5 RF_RST - RF Synthesizer Counter Reset (R0[21])

The RF_RST bit resets the RF_A, RF_B and RF_R counters. After removing the reset, the RF_A and RF_B counters resume counting in close alignment with the RF_R counter. The maximum error is one prescaler cycle.

2.5 R1 REGISTER

The R1 register contains the RF_A, RF_B, RF_P, and RF_PD control words. The RF_A and RF_B control words are used to setup the programmable feedback divider. The detailed descriptions and programming information for each control word is discussed in the following sections.

2.5.1 LMX243x RF Synthesizer Swallow Counter

2.5.1.1 RF_A[3:0] - LMX2430/33 RF Synthesizer Swallow Counter (A Counter) (R1[6:3])

The RF_A control word is used to setup the RF synthesizer's A counter. For both the LMX2430 and LMX2433, the A counter is a 4-bit swallow counter used in the programmable feedback divider. The RF_A control word can be programmed to values ranging from 0 to 15.

2.5.1.2 RF_A[4:0] - LMX2434 RF Synthesizer Swallow Counter (A Counter) (R1[7:3])

The LMX2434 A counter is a 5-bit swallow counter used in the programmable feedback divider. The RF_A control word can be programmed to values ranging from 0 to 31.

2.5.2 LMX243x RF Synthesizer Programmable Binary Counter

2.5.2.1 RF_B[14:0] - LMX2430/33 RF Synthesizer Programmable Binary Counter (B Counter) (R1[21:7])

The RF_B control word is used to setup the RF synthesizer's B counter. For both the LMX2430 and LMX2433, the B counter is a 15-bit programmable binary counter used in the programmable feedback divider. The RF_B control word can be programmed to values ranging from 3 to 32767. Divide ratios less than 3 are prohibited.

2.5.2.2 RF_B[13:0] - LMX2434 RF Synthesizer Programmable Binary Counter (B Counter) (R1[21:8])

The LMX2434 B counter is a 14-bit programmable binary counter used in the programmable feedback divider. The RF_B control word can be programmed to values ranging from 3 to 16383. Divide ratios less than 3 are prohibited.

2.5.3 LMX243x RF Synthesizer Prescaler Select

2.5.3.1 RF_P - LMX2430/33 RF Synthesizer Prescaler Select (R1[22])

Both the LMX2430 and LMX2433 RF synthesizers utilize a selectable dual modulus prescaler. An 8/9 or a 16/17 prescale ratio can be selected.

2.5.3.2 RF_P - LMX2434 RF Synthesizer Prescaler Select (R1[22])

The LMX2434 RF synthesizer utilizes a selectable dual modulus prescaler. A 16/17 or a 32/33 prescale ratio can be selected.

2.5.4 RF_PD - RF Synthesizer Powerdown (R1[23])

The RF_PD bit is used to switch the RF PLL between a powered up and powered down mode.

Furthermore, the RF_PD bit operates in conjuction with the RF_CPT bit to set a synchronous or an asynchronous powerdown mode. Refer to **Section 2.4.4** for more details on how to program the RF_CPT bit.

2.6 R2 REGISTER

The R2 Register contains the RF_TOC control word. The RF_TOC is used to setup the RF syhnthesizer's Fastlock circuitry. The RF_TOC is a 12-bit binary counter programmable from 0 to 4095.

2.6.1 RF_TOC[0:11] - RF Synthesizer Timeout Counter (R2[14:3])

The FLoutRF pin can be configured as a general purpose CMOS TRI-STATE output or as a Fastlock output by programming the RF_TOC appropriately. When the RF_TOC is programmed from 0 to 3, Automatic Fastlock is disabled, and the FLoutRF pin is either configured as a general purpose CMOS TRI-STATE output or Manual Fastlock is enabled. When the RF_TOC is programmed to 0, the FLoutRF pin will be in TRI-STATE (high impedance) mode. The charge pump current is then the value specified by RF_CPG (R0[19]). When the RF_TOC is programmed to 1, the FLoutRF pin is pulled to a LOW state. The charge pump current is then set to a HIGH gain state (RF_CPG bit = 1). This condition is known as the Manual Fastlock. When the RF_TOC is programmed to 2, the FLout_RF pin will again be pulled to a LOW state, but this time the charge pump current is the value specified by RF_CPG (R0[19]). When the RF_TOC is programmed to 3, the FLoutRF pin is pulled to a HIGH state. Again, the charge pump current is the value specified by RF_CPG (R0[19]). When the RF_TOC is programmed from 4 to 4095, Fastlock is enabled and the FLoutRF pin is pulled to a LOW state. Fastlock will time-out after the specified number of PFD events. At this time, the FLoutRF pin will switch to TRI-STATE (high impedance) mode. The value programmed into RF_TOC represents the number of PFD events that the RF synthesizer will spend in the Fastlock state. Note that any write to the RF_TOC requires a PFD event on the RF synthesizer to latch the contents. This means that writes to the RF_TOC take effect synchronously with the next PFD event.

2.7 R3 REGISTER

The R3 register contains the IF_R, IF_CPP, IF_CPG, IF_CPT, and IF_RST control words, in addition to two of the four bits that compose the MUX control word. The detailed descriptions and programming information for each control word is discussed in the following sections.

2.7.1 IF_R[14:0] - IF Synthesizer Programmable Reference Divider (R Counter) (R3[17:3])

The IF reference divider (IF_R) can be programmed to support divide ratios from 3 to 32767. Divide ratios less than 3 are prohibited.

2.7.2 IF_CPP - IF Synthesizer Phase Detector Polarity (R3[18])

The IF_CPP bit is used to control the IF synthesizer's phase/ frequency detector polarity based on the VCO tuning characteristics.

IF VCO Characteristics

2.7.3 IF_CPG - IF Synthesizer Charge Pump Current Gain (R3[19])

The IF_CPG bit controls the IF synthesizer's charge pump gain. Two gain levels are available.

2.7.4 IF_CPT - IF Synthesizer Charge Pump TRI-STATE (R3[20])

The IF CPT bit allows the charge pump to be switched between a normal operating mode and a high impedance output state. This happens asynchronously with the change in the IF_CPT bit.

Furthermore, the IF_CPT bit operates in conjuction with the IF_PD bit to set a synchronous or an asynchronous powerdown mode. Refer to **Section 2.8.4** for more details on how to program the IF_PD bit.

2.7.5 IF_RST - IF Synthesizer Counter Reset (R3[21])

The IF_RST bit resets of the IF_A, IF_B and IF_R counters. After removing the reset, the IF_A and IF_B counters resume counting in close alignment with the IF_R counter. The maximum error is one prescaler cycle.

2.8 R4 REGISTER

The R4 register contains the IF_A, IF_B, IF_P, and IF_PD control words. The IF_A and IF_B control words are used to setup the programmable feedback divider. The detailed descriptions and programming information for each control word is discussed in the following sections. R4[21] is always set to 0.

2.8.1 IF_A[3:0] - IF Synthesizer Swallow Counter (A Counter) (R4[6:3])

The IF_A control word is used to setup the IF synthesizer's A counter. The A counter is a 4-bit swallow counter used in the programmable feedback divider. The IF_A control word can be programmed to values ranging from 0 to 15.

2.8.2 IF_B[13:0] - IF Synthesizer Programmable Binary Counter (B Counter) (R4[20:7])

The IF_B control word is used to setup the IF synthesizer's B counter. The B counter is a 14-bit programmable binary counter used in the programmable feedback divider. The IF_B control word can be programmed to values ranging from 3 to 16383. Divide ratios less than 3 are prohibited.

2.8.3 IF_P - IF Synthesizer Prescaler Select (R4[22])

The LMX243x IF synthesizer utilizes a selectable dual modulus prescaler. An 8/9 or a 16/17 prescale ratio can be selected.

2.8.4 IF_PD - IF Synthesizer Powerdown (R4[23])

The IF_PD bit is used to switch the IF PLL between a powered up and powered down mode.

Furthermore, the IF_PD bit operates in conjuction with the IF_CPT bit to set a synchronous or an asynchronous powerdown mode. Refer to **Section 2.7.4** for more details on how to program the IF_CPT bit.

2.9 R5 REGISTER

The R5 Register contains the IF_TOC control word. The IF_TOC is used to setup the IF syhnthesizer's Fastlock circuitry. The IF_TOC is a 12-bit binary counter programmable from 0 to 4095.

2.9.1 IF_TOC[0:11] - IF Synthesizer Timeout Counter (R5[14:3])

The OSCout/ FLoutIF pin can be configured as a general purpose CMOS TRI-STATE output or as a Fastlock output by programming the IF_TOC appropriately. When the IF_TOC is programmed from 0 to 3, Automatic Fastlock is disabled, and the OSCout/ FLoutIF pin is configured as a general purpose CMOS TRI-STATE output or Manual Fastlock is enabled. When the IF_TOC is programmed to 0, the OSCout/ FLoutIF pin will be in TRI-STATE (high impedance) mode. The charge pump current is then the value specified by IF_CPG (R3[19]). When the IF_TOC is programmed to 1, the OSCout/ FLoutIF pin is pulled to a LOW state. The charge pump current is then set to a HIGH gain state (IF_CPG bit = 1). This condition is known as the Manual Fastlock. When the IF_TOC is programmed to 2, the OSCout/ FLout_IF pin will again be pulled to a LOW state, but this time the charge pump current is the value specified by IF_CPG (R3[19]). When the IF_TOC is programmed to 3, the OSCout/ FLoutIF pin is pulled to a HIGH state. Again, the charge pump current is the value specified by IF_CPG (R3[19]). When the IF_TOC is programmed from 4 to 4095, Fastlock is enabled and the OSCout/ FLoutIF pin is pulled to a LOW state. Fastlock will time-out after the specified number of PFD events. At this time, the OSCout/ FLoutIF pin will switch to TRI-STATE (high impedance) mode. The value programmed into IF_TOC represents the number of PFD events that the IF synthesizer will spend in the Fastlock state. Note that any write to the IF_TOC requires a PFD event on the IF synthesizer to latch the contents. This means that writes to the IF_TOC take effect synchronously with the next PFD event.

2.10 MUX[3:0] - MULTIFUNCTION OUTPUT SELECT (R3[23:22]:R0[23:22])

The MUX control word is used to determine which signal is routed to the Ftest/LD pin.

LMX2430/LMX2433/LMX2434 **LMX2430/LMX2433/LMX2434**

Notes:

1. $RF_N = (RF_B * RF_P) + RF_A$ 2. $IF_N = (IF_B * IF_P) + IF_A$

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